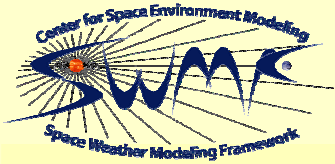


Adding New Physics and Numerics into the BATSRUS MHD Code

Gábor Tóth

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Bart van der Holst, Tamas Gombosi**

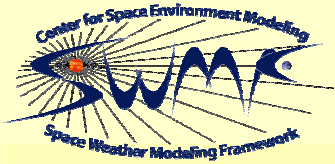
**Center for Space Environment Modeling
University Of Michigan**



Outline



- M** BATS-R-US code
- M** Space Weather Modeling Framework
- M** Two fluid MHD and non-isotropic pressure
- M** Multi-ion MHD results
- M** Local time-stepping scheme
- M** Summary



BATS-R-US

Block Adaptive Tree Solar-wind Roe Upwind Scheme



M Physics

- Classical, semi-relativistic and Hall MHD
- Multi-species, multi-fluid, anisotropic pressure
- Radiation hydrodynamics with gray diffusion
- Multi-material, non-ideal equation of state
- Solar wind turbulence

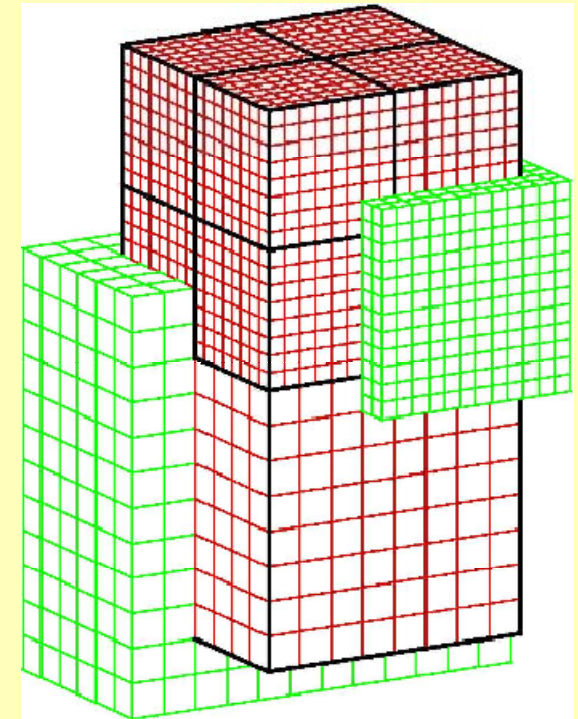
M Numerics

- Conservative finite-volume discretization
- Parallel block-adaptive grid
- Cartesian and generalized coordinates
- Splitting the magnetic field into $B_0 + B_1$
- Divergence B control: 8-wave, CT, projection, parabolic/hyperbolic
- Shock-capturing TVD schemes: Rusanov, HLLE, AW, Roe, HLLD
- Explicit, point-implicit, semi-implicit, fully implicit time stepping

M Applications

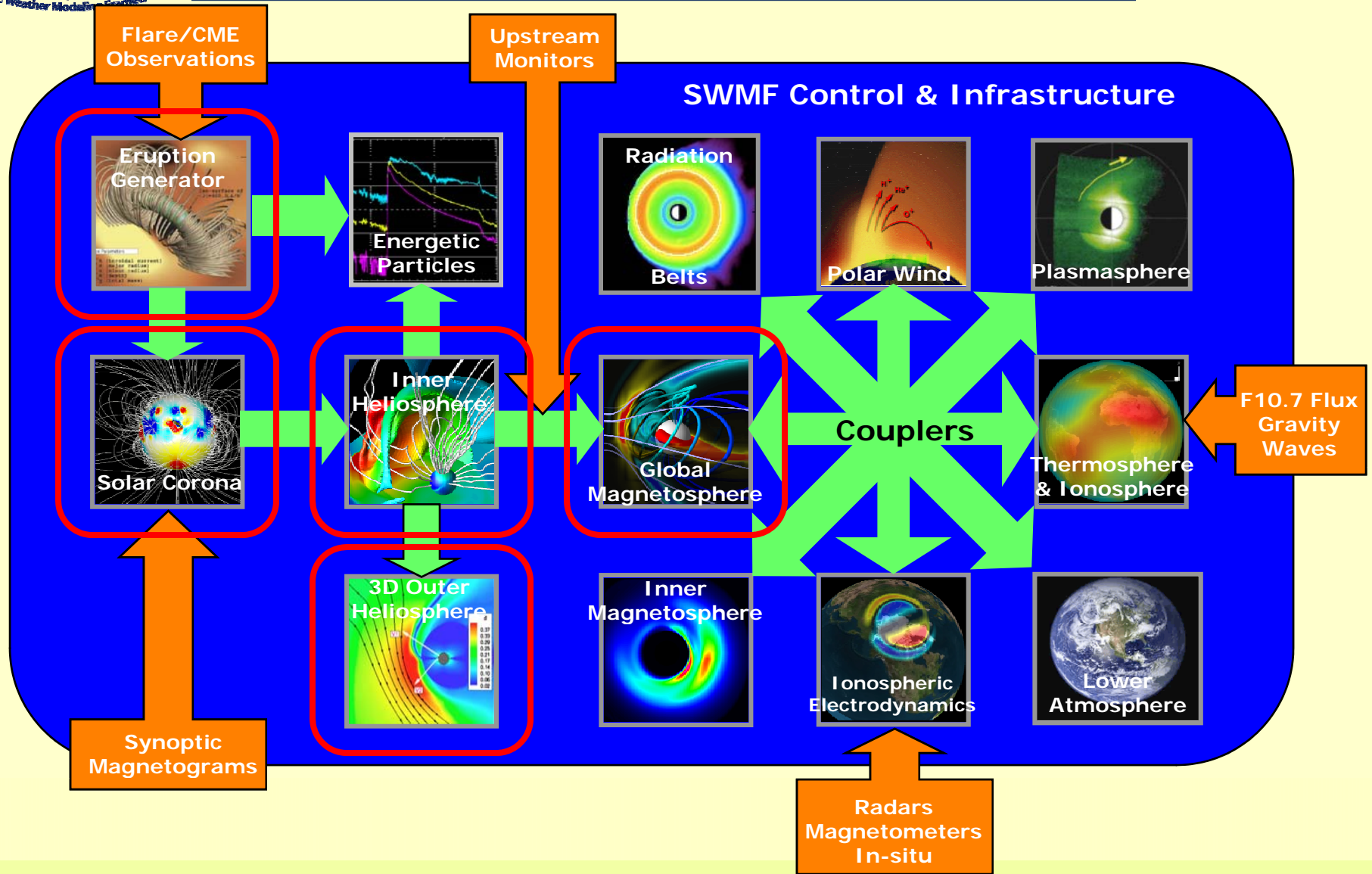
- Sun, heliosphere, magnetosphere, unmagnetized planets, moons, comets...

M 100,000+ lines of Fortran 90 code with MPI parallelization

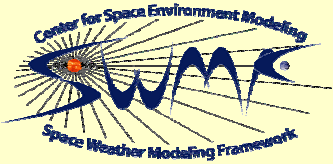




BATS-R-US in the Space Weather Modeling Framework



The SWMF is freely available at <http://csem.engin.umich.edu>



Resistive Hall MHD with electrons and anisotropic ion pressure



Mass conservation: $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$

Momentum: $\frac{\partial \rho \mathbf{u}}{\partial t} + \nabla \cdot (\rho \mathbf{u} \mathbf{u} + P \mathbf{I}) = -en_e (\mathbf{E} + \mathbf{J} \times \mathbf{B})$

$$P = (p_{\perp} + p_e) \mathbf{I} + (p_{\parallel} - p_{\perp}) \mathbf{b} \mathbf{b} \quad \mathbf{b} = \mathbf{B}/B$$

Induction: $\frac{\partial \mathbf{B}}{\partial t} + \nabla \times \mathbf{E} = 0$

Pressure: $\frac{\partial p_{\perp}}{\partial t} + \nabla \cdot (p_{\perp} \mathbf{u}) = \frac{2\eta e^2 n_e}{M_i} \left[(p - p_e) - p_{\perp} \frac{\nabla \cdot \mathbf{u}}{M_i} + \frac{3\eta e^2 n_e}{M_i} \frac{p_{\perp}}{(p_e - p)} \mathbf{b} \cdot (\nabla \mathbf{u}) \cdot \mathbf{b} \right]$

$$\frac{\partial p_{\parallel}}{\partial t} + \nabla \cdot (p_{\parallel} \mathbf{u}) = + \frac{2\eta e^2 n_e}{M_i} (p - p_e) - 2p_{\parallel} \mathbf{b} \cdot (\nabla \mathbf{u}) \cdot \mathbf{b}$$

Electron pressure:

$$\frac{\partial p_e}{\partial t} + \nabla \cdot (p_e \mathbf{u}_e) = (\gamma - 1) \left[(-p_e \nabla \cdot \mathbf{u}_e + \eta \mathbf{J}^2 + \frac{3\eta e^2 n_e}{M_i} (p - p_e) + \nabla \cdot (\kappa \mathbf{b} \mathbf{b} \cdot \nabla T_e) \right]$$

Electron velocity: $\mathbf{u}_e = \mathbf{u} - \frac{\mathbf{J}}{en_e}$

Electric field: $\mathbf{E} = -\mathbf{u} \times \mathbf{B} + \eta \mathbf{J} + \frac{\mathbf{J} \times \mathbf{B}}{en_e} - \frac{\nabla p_e}{en_e} - \frac{\nabla \cdot [\mathbf{b} \mathbf{b} (p_{\parallel} - p_{\perp})]}{en_e}$

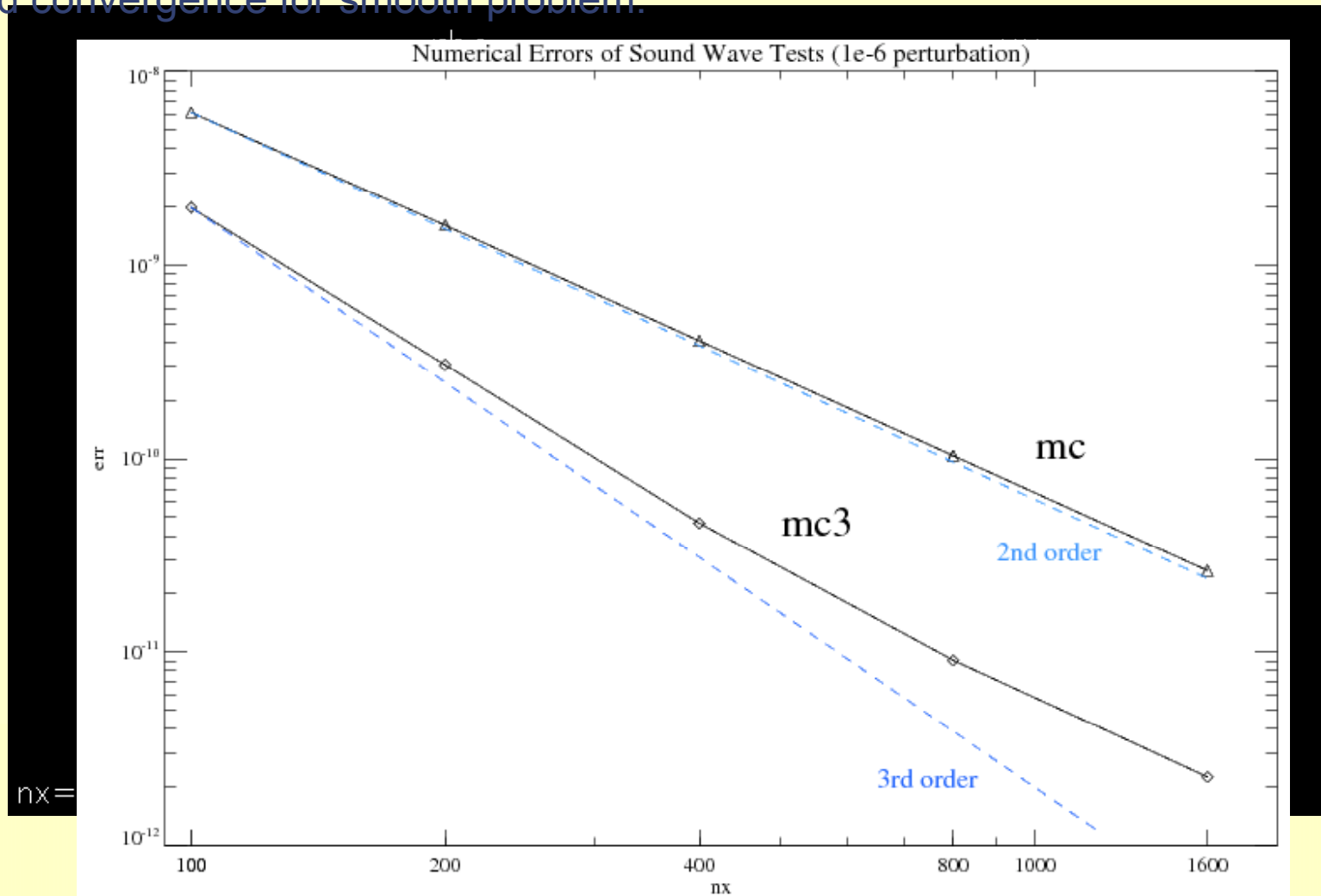
Current: $\mathbf{J} = \nabla \times \mathbf{B}$

Tests for anisotropic pressure



Sound wave propagating parallel to magnetic field at $c_s = \sqrt{3p_{\parallel}/\rho}$

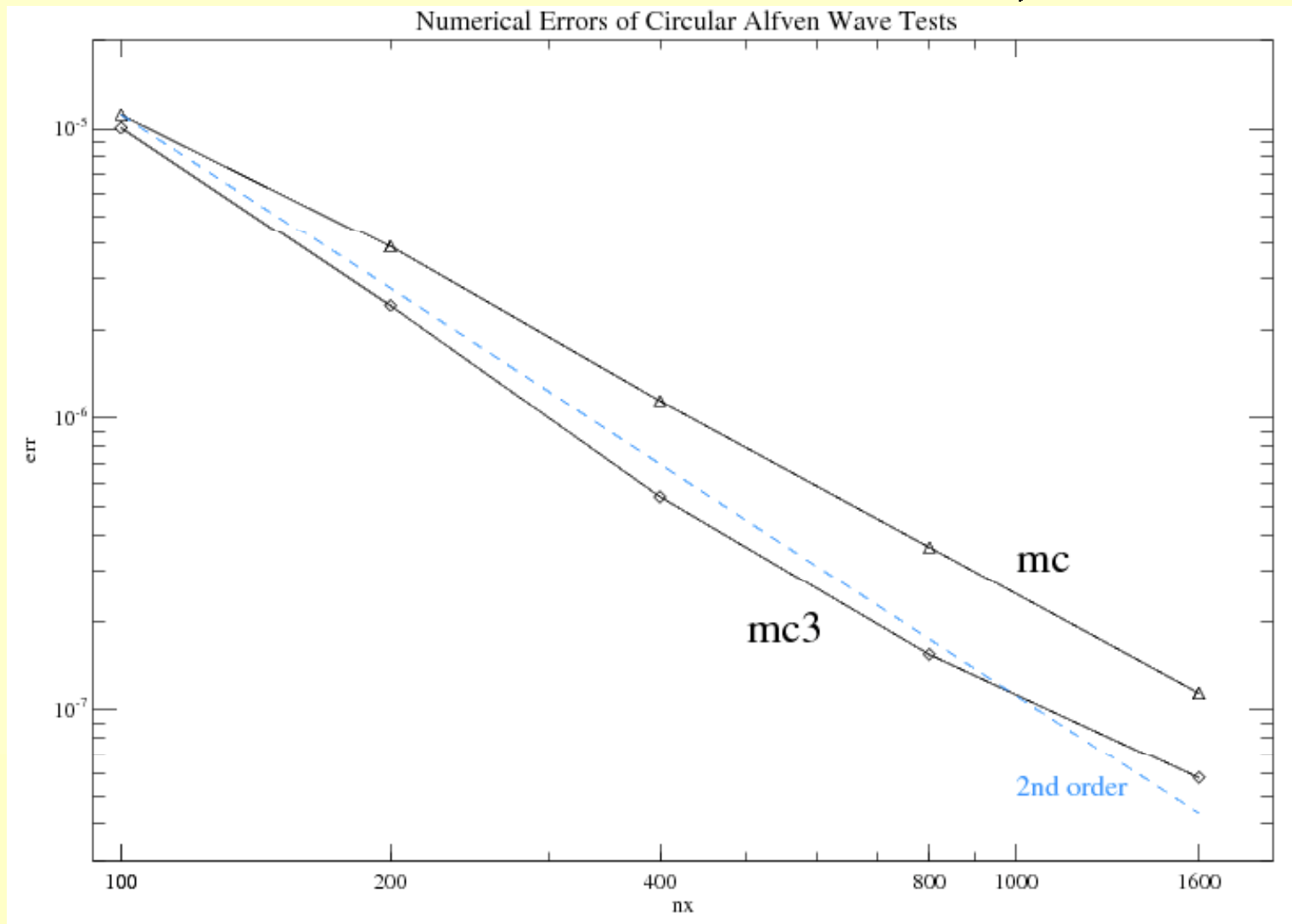
Grid convergence for smooth problem:



Tests for anisotropic pressure



Circularly polarized Alfvén wave propagating at $v_A = \sqrt{(\mathbf{B}^2 + p_{\perp} - p_{\parallel})/\rho}$



For each ion fluid s (neglecting resistive terms):

$$\frac{\partial \rho_s}{\partial t} + \nabla \cdot (\rho_s \mathbf{u}_s) = S_{\rho_s}$$

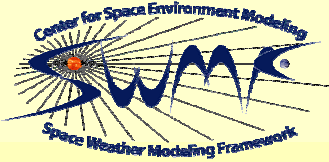
$$\frac{\partial \rho_s \mathbf{u}_s}{\partial t} + \nabla \cdot (\rho_s \mathbf{u}_s \mathbf{u}_s + I p_s) = \frac{n_s q_s}{n_e e} (\mathbf{J} \times \mathbf{B} - \nabla p_e) + n_s q_s (\mathbf{u}_s - \mathbf{u}_+) \times \mathbf{B} + S_{\rho_s \mathbf{u}_s}$$

$$\frac{\partial p_s}{\partial t} + \nabla \cdot (p_s \mathbf{u}_s) = -(\gamma - 1) p_s \nabla \cdot \mathbf{u}_s + S_{p_s}$$

Induction equation (neglecting Hall term):

$$\frac{\partial \mathbf{B}}{\partial t} - \nabla \times (\mathbf{u}_+ \times \mathbf{B}) = 0$$

where the charge-averaged ion-velocity is $\mathbf{u}_+ = \frac{\sum_s n_s q_s \mathbf{u}_s}{en_e}$



Initial Results with Multi-Ion MHD (Glocer et al, in press)



M Modeling two magnetic storms

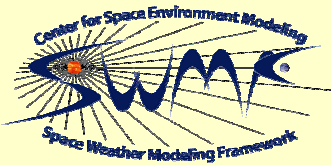
- May 4, 1998
- March 31, 2001

M Multi-fluid BATS-R-US running in the SWMF coupled with

- Polar Wind Outflow Model
- Ridley Ionosphere-electrodynamics Model
- Rice Convection Model (inner magnetosphere)

M Comparison with

- single fluid model
- global indexes (Dst, CPCP)
- in situ satellite measurements

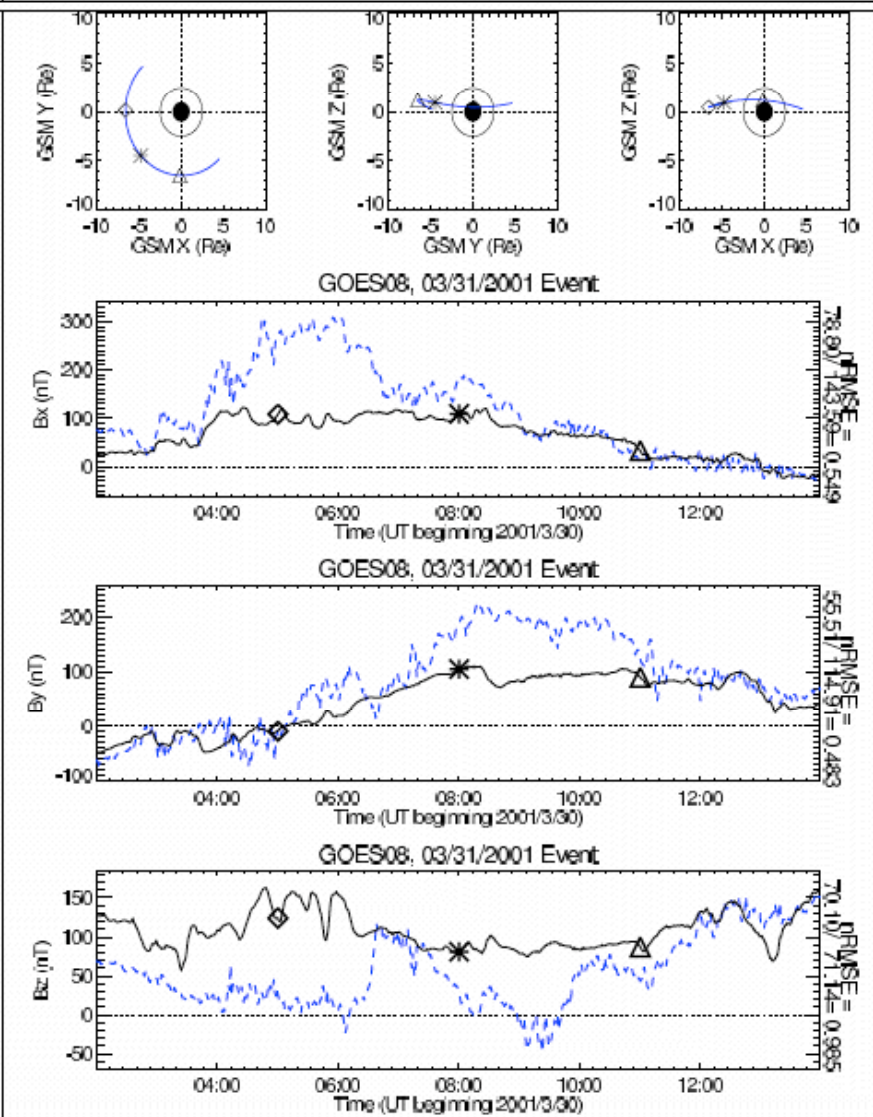
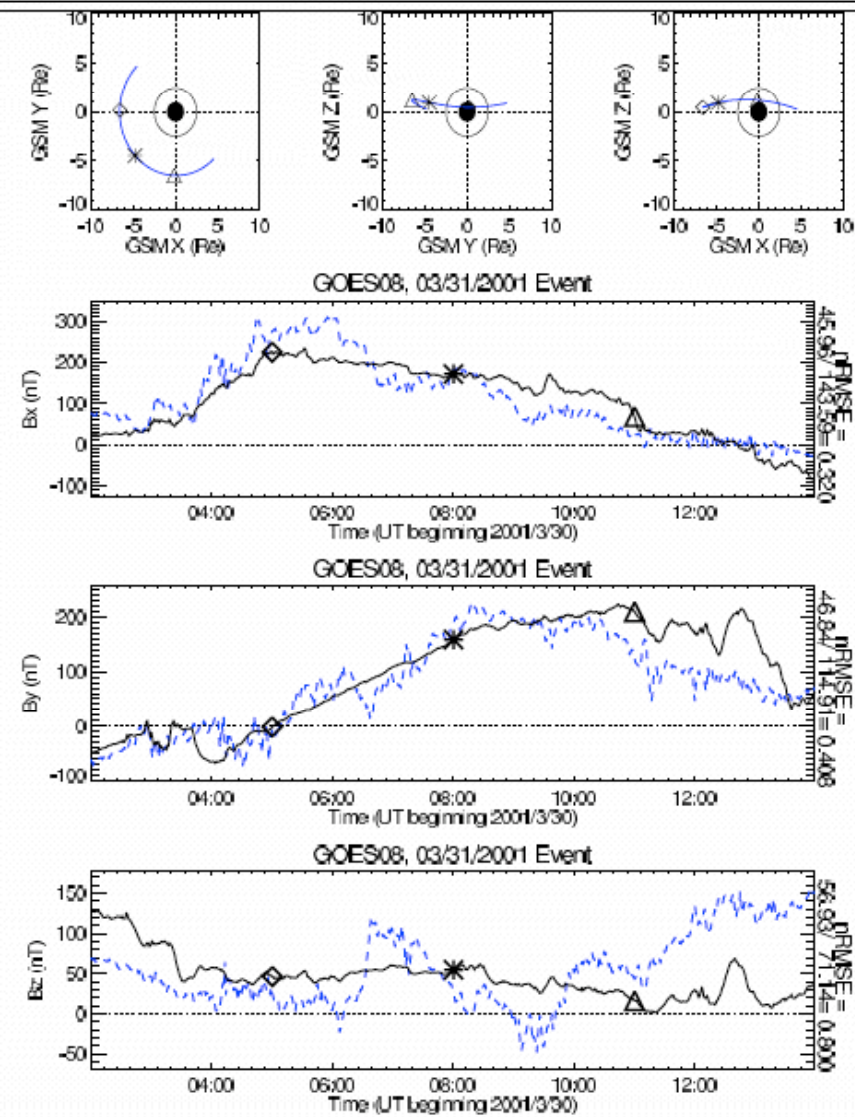


Magnetic Field vs Goes 8 Satellite

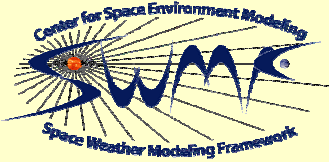


Multi-fluid MHD with O⁺ outflow

Single-fluid MHD with no outflow



Toth:



Local Time Stepping



M Time stepping schemes

- Explicit scheme with fixed time step is limited by most restrictive CFL condition
- Time step in an implicit scheme is not restricted by stability, but expensive
- **Local time stepping allows each cell/block advance in time limited by local CFL**

M Issues in Local Time Stepping algorithm

- Time interpolation (and extrapolation!) of ghost cells
- Order of advancing the cells
- Load balancing
- Conservative flux correction

M Choices in Local Time Stepping algorithm

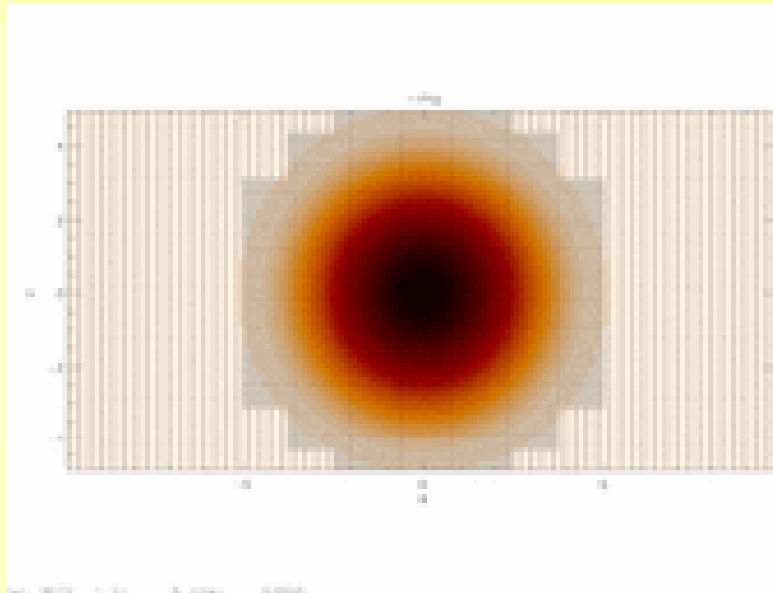
- Local time step is proportional to grid cell size (Berger and Colella)
 - + relatively simple
 - not optimal if the fastest wave speed varies a lot in the computational domain
- Local time step set by CFL condition and rate of change (Omelchenko et al)
 - + optimal time step
 - + stability is guaranteed
 - complicated, difficult scheduling and load balancing
 - multiple flux calculations between cells with similar time steps
- Local time step set by CFL condition, but rounded to powers of 2 fractions (Flaherty et al., Crossley and Wright)
 - + close to optimal time step (within factor of 2)
 - + simpler scheduling and load balancing
 - + few extra flux calculations
 - have to be careful about stability

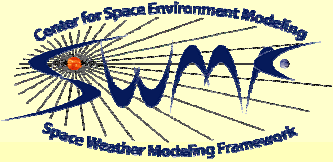
M Current status

- Local time step is set on a block by block basis based on grid level
- Each level is load balanced separately

M Plan

- Eventually use powers of 2 time steps based on local block CFL condition
- Possibly check stability condition during global time step and change local time step if needed, but no load balancing at this stage





Summary

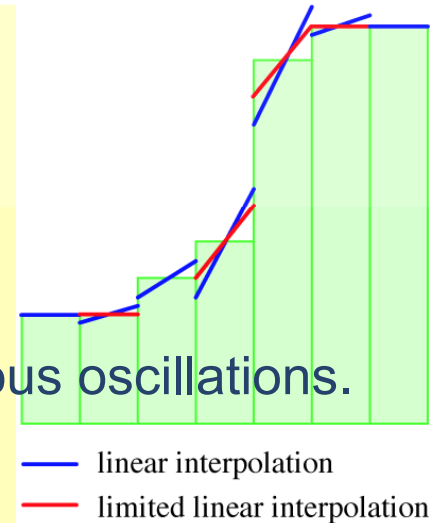


- M** Added two-fluid (electron + ion) and anisotropic MHD to BATS-R-US.
- M** Initial verification tests pass for anisotropic pressure MHD.
- M** First multi-ion MHD results are now published (Glocer et al, JGR).
- M** Prototype local time stepping scheme has been implemented.

Numerical Diffusion

M Numerical diffusion is useful

- Explicit scheme: needed for stability and to avoid spurious oscillations.
- Implicit scheme: needed to avoid spurious oscillations.
- High order schemes have less diffusion in well resolved regions only.



M Total Variation Diminishing (TVD) schemes

- $F_{\text{diff}} = |\lambda| (U_R - U_L)/2$
- Here U_R and U_L are the right and left states and λ is the wave speed, that is the Alfvén speed for the magnetic field.
- $U_R - U_L$ is proportional to $(\Delta x)^n$ where n is the order of the scheme.
- Near fast changing gradients and at local extrema TVD schemes become first order accurate: $U_R - U_L \approx \Delta x \, dU/dx$

M Typical affordable grid resolution near Earth is $1/4 R_E$ to $1/8 R_E$

- Far from well resolved, so first order numerical diffusion dominates.

M Semi-relativistic correction

- Classical Alfvén speed $v_A = B / \sqrt{\mu_0 \rho}$ can exceed speed of light c .
- Boris (also Gombosi et al.) derived the semi-relativistic MHD equations, where

$$v_A^{semi} = \frac{v_A}{\sqrt{1 + v_A^2/c^2}}$$

- The semi-relativistic formulation is necessary for Saturn or Jupiter.

M Reducing the speed of light

- One can replace c with a reduced c' , e.g. $c' = 0.01 c = 3000\text{km/s}$
- + Allows larger time steps for explicit time stepping
- + Reduces the numerical diffusion by reducing $\lambda \approx v_A$!
- - Changes the time accurate behavior of the MHD equations...
- Artificial reduction of c is used in many magnetosphere codes

M New idea: limit diffusive flux in the implicit TVD scheme

- $F_{\text{diff}} = |\lambda'| (U_R - U_L)/2$ and $|\lambda'| = \min(\lambda_{\text{max}}, |\lambda|)$
- λ_{max} can be set to any value, e.g. 2000km/s for magnetosphere simulation
- + Numerical diffusion is reduced
- + The physical behavior of the MHD equations is not modified
- - Oscillation-free property is not guaranteed. But in practice, it seems to work.

M Test: May 1998 magnetic storm

- Both Boris correction and limited numerical diffusion results in more negative Dst.
- Closer to observations.

