#### Learning to Knowledge Discovery to Action in Distribution Sensitive Scenarios NASA CIDU, Oct 15<sup>th</sup>, 2009



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Typical Prediction Mode Nitesh Chawla, NASA CIDU, October 15, 2009

#### **Paradox of False Positive**

Imagine a disease that has a prevalence of 1 in a mllion people. I invent a test that is 99% accurate. I am obviously excited. But, when applied to a million, it returns positive for 10,000 (remember, it is 99%accurate). Priors tell us otherwise. There is one in a million infected --- 99% accurate test is inaccurate 9,999 times out of 10,0000.

"Although the rare events' consequences can be enormous, such events are very difficult to predict based on past data...."

"The available data are often scarce, because such events are necessarily unusual, and careful and sophisticated modeling is needed to extract the fullest information from the data, and to provide realistic forecasts and associated measures of uncertainty."

#### The statistic of rare event



#### That needle in the Haystack

### The one in a 100, one in a 1000, one in 100,000, and one in a million event

- Fraud detection
- Disease prediction
- Intrusion detection
- Text categorization
- Bioinformatics
- Direct marketing
- Terrorism
- Physics simulations
- Climate



#### Learning from Imbalanced Data (Rare Event)

Data set is considered imbalanced, if the classes are unequally distributed

Class of interest (minority class) is often much infrequent or rarer

But, the cost of error on the minority class has a bigger bite



IEEE ICDM noted "Dealing with Non-static, Unbalanced and Cost-sensitive Data" among the 10 Challenging Problems in Data Mining Research



#### Typical Prediction Mode Nitesh Chawla, NASA CIDU, October 15, 2009

		enefit	S	Predict	Actual Negative	Actual Positive
	Actual Negative	Actual Positive		Vegative Predict Positive	FP	ТР
Predict Negative	b00	b01		$B_N =$	$(1-P_k)b_0$	$_{0} + P_{k}b_{01}$
Predict Positive	b10	b11		$B_P = ($	$(1-P_k)b_1$	$_{0} + P_{k}b_{11}$

Benefit of Non-Default  $b_{00}(k,x)(1-P_k) > (1-P_k)b_{10} + P_kb_{11} - P_kb_{01}(x)$  $b_{00}(k,x) > \frac{(1-P_k)b_{10} + P_k b_{11} - P_k b_{01}(x)}{(1-P_k)}$  $NPV = (1-P_k)b_{00} - (1-P_k)b_{01} + P_kb_{11} - P_kb_{10}$  $\equiv (1 - P_k)b(TN) - (1 - P_k).C(FP) + P_k.b(TP) - P_k.C(FN)$ Liu and Chawla, "Benefit Scoring for Pricing," KDD 2007 Nitesh Chawla, NASA CIDU, October 15, 2009

#### **Solution**

- Sampling Methods
- Moving Decision Threshold
- Classifiers' Objective Functions

#### Undersampling

Randomly remove majority class examples



Risk of losing potentially important majority class examples, that help establish the discriminating power

#### **Oversampling**

Replicate the minority class examples to increase their relevance



But no new information is being added. Hurts the generalization capacity.

## Instead of replicating, let us invent some new instances

 SMOTE: Synthetic Minority Over-sampling Technique



#### Conclusions from Sampling Work:

- When faced with the problem of class imbalance, SMOTE and undersampling, is generally the preferred combination.
- Using a wrapper can effectively discover the potentially optimally amounts of sampling.
- Effectively countering imbalance counters misclassification costs issues

Chawla, et al., "SMOTE: Synthetic Minority Oversampling Technique, *Journal of Artificial Intelligence Research*,

Cieslak, Chawla, "Start Globally, Optimize Locally, and Predict Globally: Improving Performance on Imbalanced Data," *IEEE International Conference on Data Mining (ICDM)*, 2007

Chawla et al., "Automatically countering class imbalance and its empirical relationship to cost, *Data Mining and Knowledge Discovery Journal*, 2009

- Sampling approaches can be computationally expensive
- Outstanding Question: How to improve the baseline classifier performance?

Specifically, making decision trees skew insensitive

#### **Beyond Sampling**

- Traditional decision tree splitting criteria are typically class skew sensitive
  - Almost always need some sampling or threshold moving
  - Ensemble methods can potentially mitigate but can be limited

#### **Looking at Decision Trees**

#### **Decision Trees**

- A popular choice when combined with sampling or moving threshold to counter the problem of class imbalance
- The leaf frequencies converted to probability estimates (Laplace or mestimate smoothing applied, typically)
  - Suggested use is as a PET Probability Estimation Trees (unpruned, no-collapse, and Laplace)

#### Entropy (Information Gain) as an impurity

- (Q,W) classes of interest
  - N = number of samples

$$N_i$$
 = number of samples in class  $i$ 

$$V^{S}$$
 = number of samples in  $L/R$ 

 $N_i^S$  = number of samples in class i is L/R split

$$E = \sum_{i \in (W,Q)} -\frac{N_{i}^{L}}{N^{L}} \log_{2} \frac{N_{i}^{L}}{N^{L}} + \sum_{i \in (W,Q)} -\frac{N_{i}^{R}}{N^{R}} \log_{2} \frac{N_{i}^{R}}{N^{R}}$$

# Proposing Hellinger distance for decision tree splitting criterion

#### Hellinger Distance

 distance between probability measures independent of the dominating parameters

#### **Properties of Hellinger Distance**

$$d_{H}(P,Q) = \sqrt{\int_{\Omega} (\sqrt{P} - \sqrt{Q})^{2} d\lambda}$$

$$d_H(P,Q) = \sqrt{\sum_{\phi \in \Phi} (\sqrt{P(\phi)} - \sqrt{Q(\phi)})^2}$$

- Measures countable space Φ
- Ranges from 0 to  $\sqrt{2}$
- Symmetric:  $d_H(P,Q) = d_H(Q,P)$
- Lower bounds KL divergence

#### Inf. Gain vs. Hellinger distance

(Q,W) classes of interest N $N_i$  = number of samples in class *i*  $N^S$ = number of samples in L/R $N_i^S$ = number of samples in class i is L/Rsplit  $E = \sum_{i \in (W,Q)} -\frac{N_{i}^{L}}{N^{L}} \log_{2} \frac{N_{i}^{L}}{N^{L}} + \sum_{i \in (W,Q)} -\frac{N_{i}^{R}}{N^{R}} \log_{2} \frac{N_{i}^{R}}{N^{R}}$  $H = \sqrt{\left\{ \left\{ \frac{N_Q^L}{N_Q} - \sqrt{\frac{N_W^L}{N_W}} \right\}^2 + \left\{ \sqrt{\frac{N_Q^R}{N_Q}} - \sqrt{\frac{N_W^R}{N_W}} \right\}^2 \right\}}$ 

## Hellinger as decision tree splitting criterion

$$d_{H} = \sqrt{(\sqrt{P(L|+)} - \sqrt{P(L|-)})^{2} + (\sqrt{P(R|+)} - \sqrt{P(R|-)})^{2}}$$

$$d_{H} = \sqrt{2 - 2\sqrt{P(L|+)P(L|-)} - 2\sqrt{P(R|+)P(R|-)}}$$

$$d_{H} = \sqrt{(\sqrt{tpr} - \sqrt{fpr})^{2} + (\sqrt{1 - tpr} - \sqrt{(1 - fpr)^{2}})^{2}}$$

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2009

#### **Comparing Value Surfaces**



### **Comparing Value Surfaces**





Hellinger Information Gain Distance Class ratio +:- = 1:100

- 19 data sets from a number of domains and applications
  - Detecting oil spills, mammography, forest cover type, drug discovery, bioinformatics, satellite images, etc.
  - And public repository (UCI)
- 5x2 fold cross-validation
- AUC as evaluation metric
- Friedman test to statistically evaluate the performance of classifier

#### **Empirical Evaluation**

### **HDDT Results**

	Base			Sampling			
	C4.5	Gini (CART)	HDDT	C4.5	Gini (CART)	HDDT	
Avg Rank	5.61	7.42	2.50	4.00	6.18	3.79	
Friedman							
95%							
conf	$\checkmark$	$\checkmark$			$\checkmark$		
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#### **But More Can Be Better**

- Traditional: Use 100% of training data to build a sage.
- Ensemble: Randomize training data to build many voted experts ("bagging").
- Boosting: Emphasize difficult instances in future iterations

#### One sage sees all the data



#### Many experts see 2/3's of the data



Experts outperform the sage!

#### Imbalanced Data

### 38 Datasets from multiple domains and applications.

Key

- T: Single Tree
- **B: Bagging**
- BT: Boosting

Hellinger Distance (HD) AUC Ranks

	В	Т	Bt
Average Rank	5.10	14.95	7.16
90% Confidence		$\checkmark$	
95% Confidence		$\checkmark$	
99% Confidence		$\checkmark$	

#### **Imbalanced** Data

Which bagging wins?

	HD+B	IG+B
Dataset Wins	16	4
Rank Sum	163	27
Wilcoxon Winner at 95%	$\checkmark$	

**Confirmed hypothesis:** "Hellinger distance with bagging statistically significantly performs best on unbalanced datasets."

#### **Conclusions v1.1**

If you are learning on imbalanced data, use bagged Hellinger Distance Decision Trees.

#### **Balanced Data**

**Determined Accuracy for each method on 29 balanced datasets.** 

	HD+Bt	HD+B	IG+Bt	IG+B
Average Rank	2.16	3.03	2.12	3.03
90% Confidence				
95% Confidence				
99% Confidence				

**Confirmed hypothesis:** "Hellinger distance with bagging does not perform statistically significantly worse on balanced datasets."

#### Conclusions

If you are learning on imbalanced data, use bagged Hellinger Distance Decision Trees.

If you are learning on balanced data, you may also use bagged Hellinger Distance Decision Trees.

Cieslak and Chawla, "Learning Hellinger Distance Decision Trees for Imbalanced Data," European Conference on Machine Learning, 2008

Cieslak and Chawla, "Learning robust and skew insensitive decision trees," *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, UNDER REVIEW.

But, what can I really say about the performance of my favorite model.

Optimal decisions, while they can maximize performance in static environments, can result in fragility for complex, uncertain, and rapidly changing problems.

 Manage the Tipping Point: Prepare for, React to, Manage the Predictive
Uncertainties

#### **Grand Challenge Problem**

### **Tipping Point Grand Challenge**

- Can we anticipate the impact of potential changes in distribution?
- Can we gauge the impact of those to different performance estimates?
- Can we appropriately weigh and select models for use?

## First, let us consider some common steps of model development





#### **Detail is in the Design of Experimentation**

- Model Monitor Evaluating and Monitoring Models
- You can download from <u>http://www.nd.edu/~dial</u>

Cieslak, Chawla, "Detecting Fractures in Classifier Performance," *IEEE International Conference on Data Mining (ICDM)*, 2007

Cieslak, Chawla, "A Framework for Monitoring Classifiers' Performance: When and Why Failure Occurs?," *Knowledge and Information Systems Journal*, 2008

Raeder, Chawla, "Model Monitor: Evaluating, Comparing and Monitoring Models," *Journal of Machine Learning Research*, 2009

Let neither measurement without theory Nor theory without measurement dominate Your mind but rather contemplate A two-way interaction between the two Which will your thought processes stimulate To attain syntheses beyond a rational expectation!

Contributed by A. Zellner.



#### Thank you

- Questions?
- For papers
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