

1st Aeroelastic Prediction Workshop

Static and Forced Motion Simulations of the HIRENASD Test Case- Approaches and Results

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Knowledge for Tomorrow



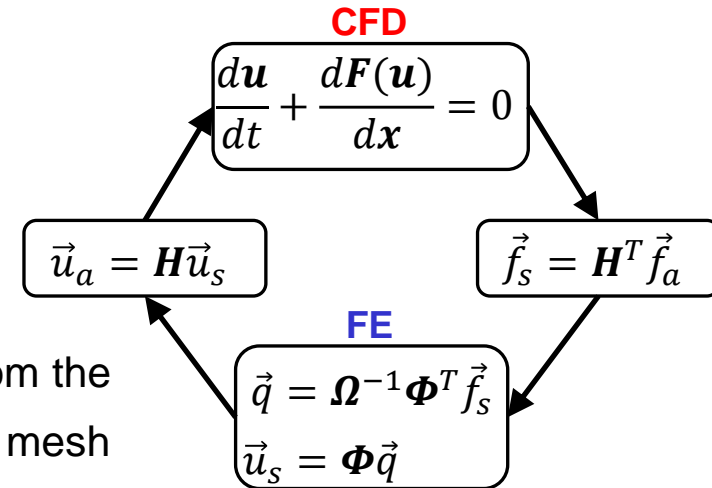
Approach for the static coupling simulations

- For steady calculations, the flexibility of the wing was taken into account by applying a weakly coupled FSI simulation based on a modal approach

$$\mathbf{\Omega} \vec{q} = \mathbf{\Phi}^T \vec{f}_s \quad \mathbf{\Omega} = \text{Eigenvalues matrix}$$

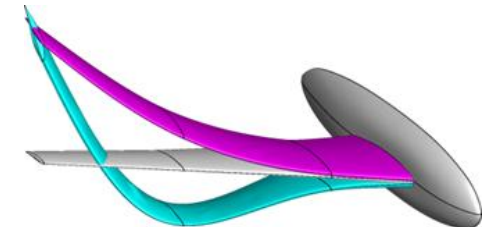
$$\vec{f}_s = \mathbf{H}^T \vec{f}_a \quad \mathbf{\Phi} = \text{Mode shape matrix}$$

$$\quad \quad \quad \mathbf{H} = \text{Interpolation matrix}$$



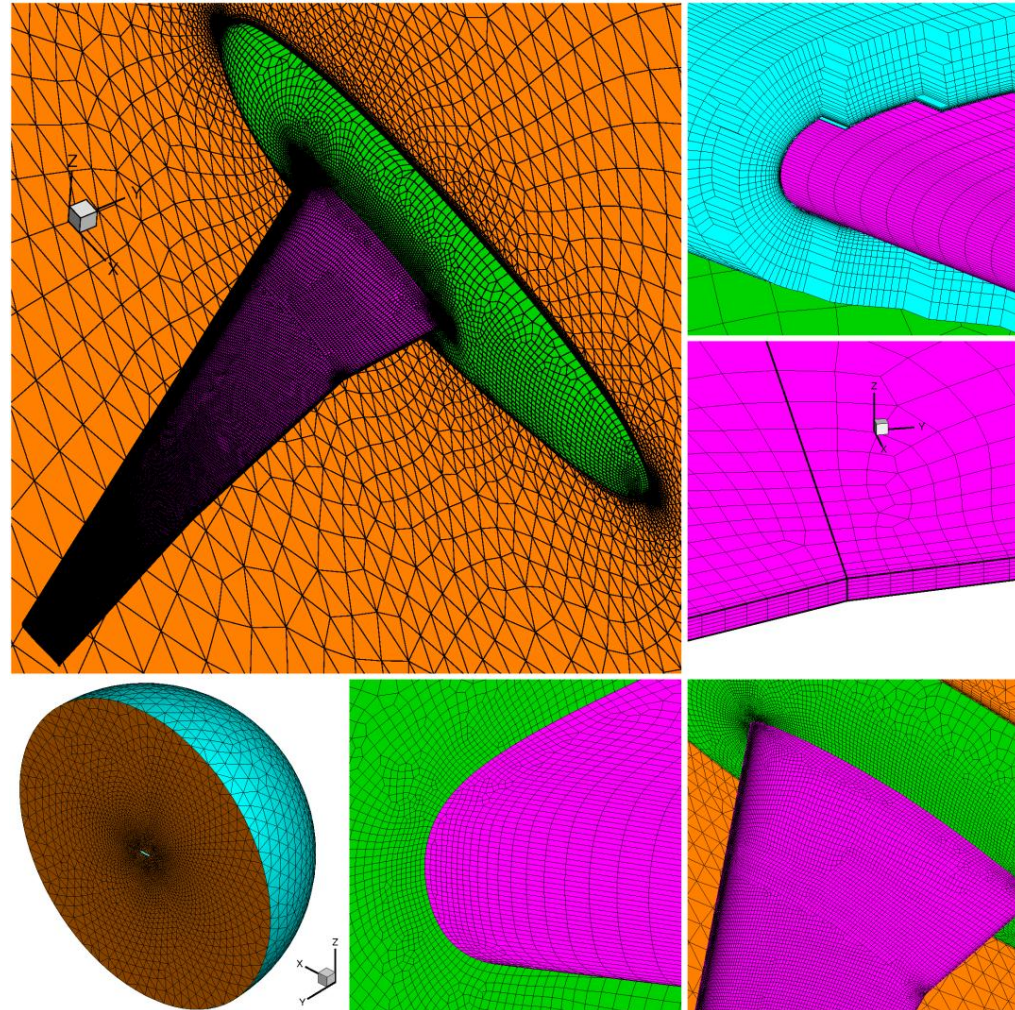
- To reduce computational costs, the mode shapes from the FE model can be interpolated onto the aerodynamic mesh in a pre-processing step

$$\vec{q} = \mathbf{\Omega}^{-1} (\mathbf{H}\mathbf{\Phi})^T \vec{f}_a = \mathbf{\Omega}^{-1} \mathbf{\Phi}_a^T \vec{f}_a \quad \mathbf{\Phi}_a^T = \text{Aerodynamic mode shape matrix}$$



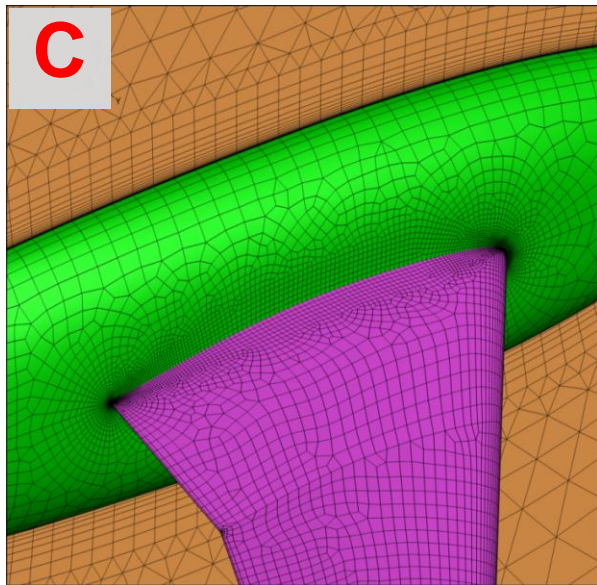
Numerical models used for the simulations

- Any aerodynamic simulations were done by the DLR TAU code, a node-based, finite-volume flow solver in ALE formulation working with hybrid grids
- Unstructured, *quad dominant* CFD meshes generated by Solar were used
- No wind tunnel walls were modeled, but a hemispherical farfield was applied

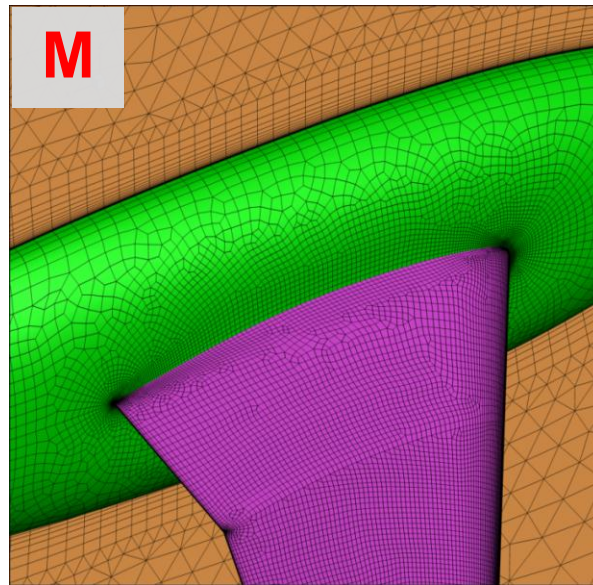


Numerical models used for the simulations

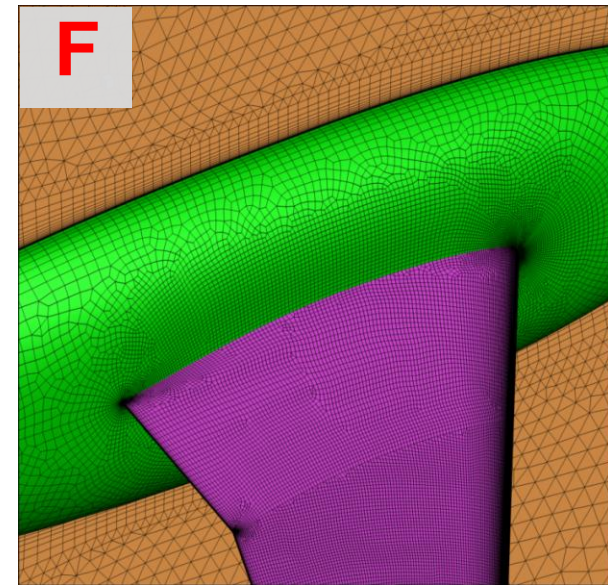
- Three different grids:



Nodes : 1 million



2.4 million

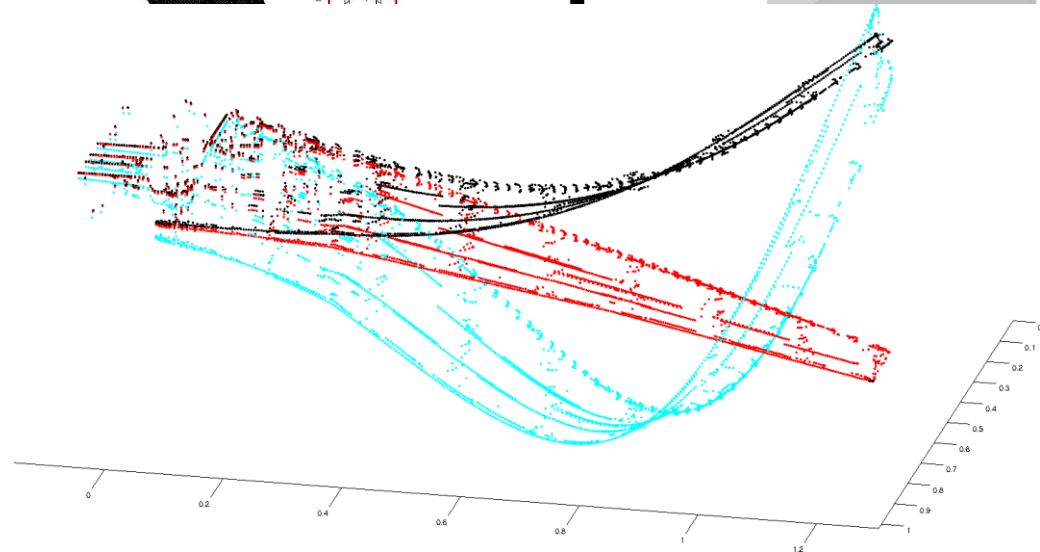
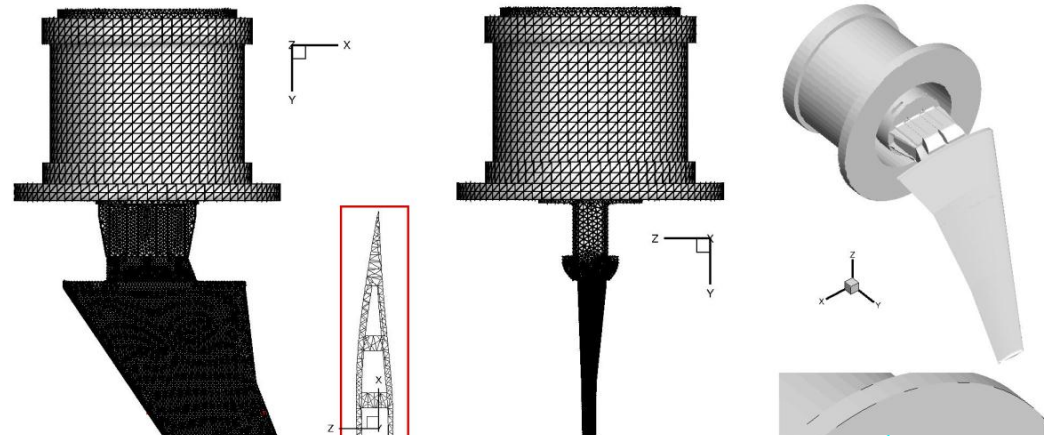


7.2 million



-Numerical models used for the simulations

- The FE model designed by NASA that includes the balance housing was used
- NASTRAN SOL 103 is used to obtain modeshapes and eigenvalues
- Number of points was reduced using a kd-tree based method
- For the static coupling simulations, a modal basis of the twenty lowest modes was used



Numerical models used for the simulations

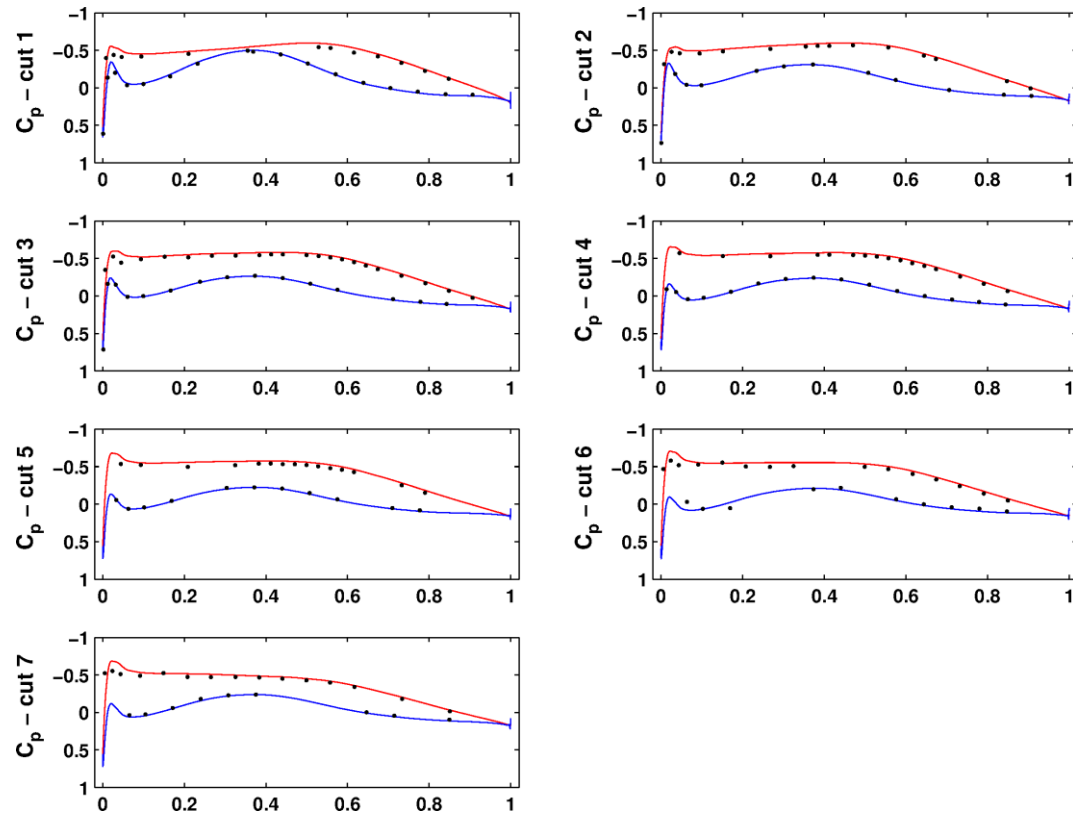
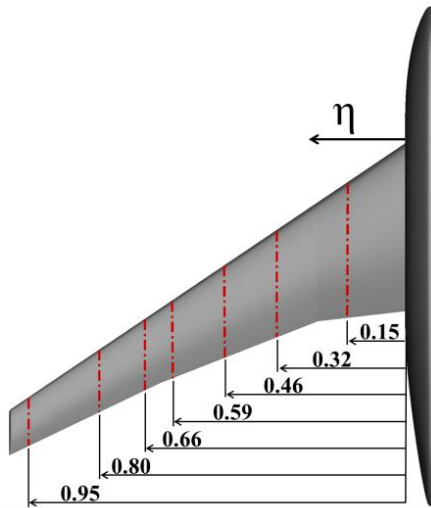
- Settings applied to the TAU code:
 - Inviscid flux calculation by Central differences (JST Scheme) with scalar dissipation
 - Convergence acceleration by multigrid
 - Local/dual time stepping for steady/unsteady simulations
 - Any calculations (RANS/URANS) used the Edward's modified version of the Spalart-Allmaras turbulence model
 - Moving boundary conditions employed by Radial-Basis-Function based mesh deformation



Results and validation of the steady simulations

- Comparison of the static coupling results in terms of c_p for test case **155**

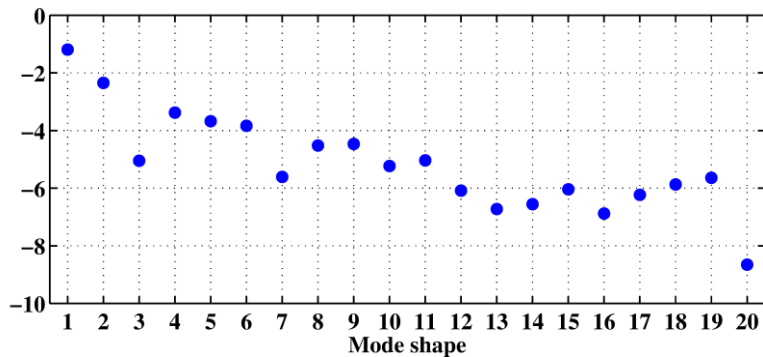
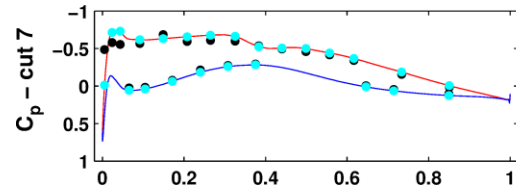
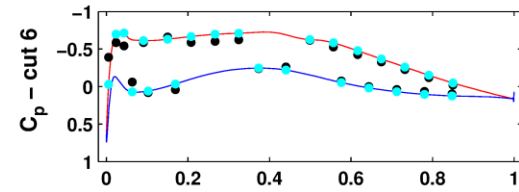
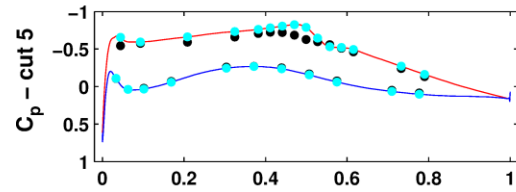
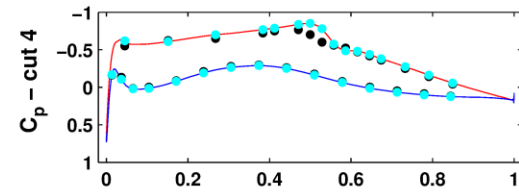
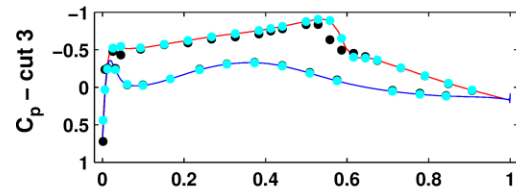
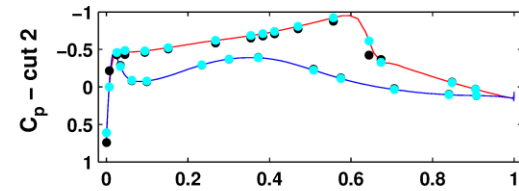
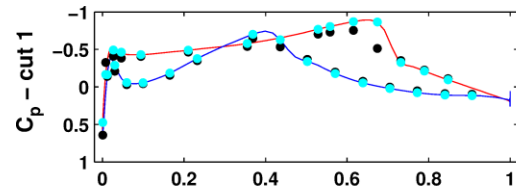
- AoA = 1.5°
- Ma = 0.7, Re = 7.0 million
- Medium mesh



Results and validation of the steady simulations

- Comparison of the static coupling results in terms of c_p for test case **159**

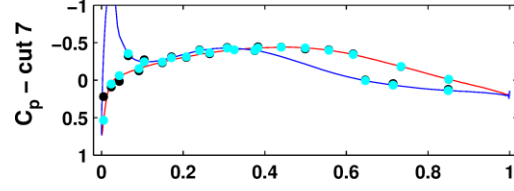
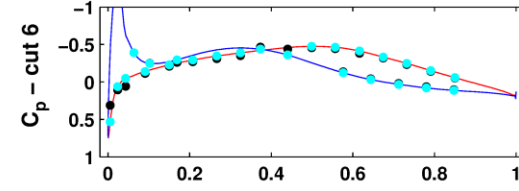
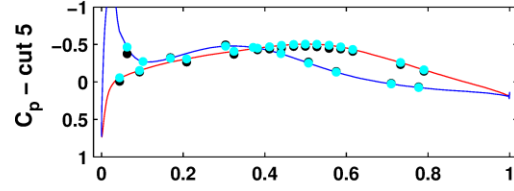
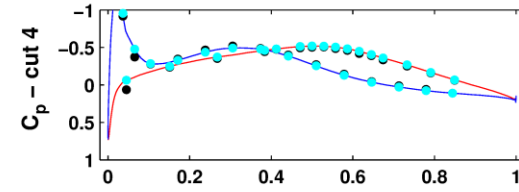
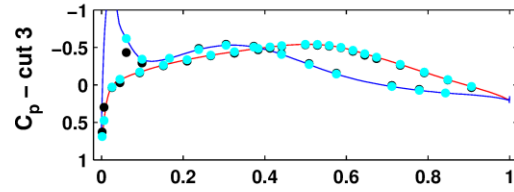
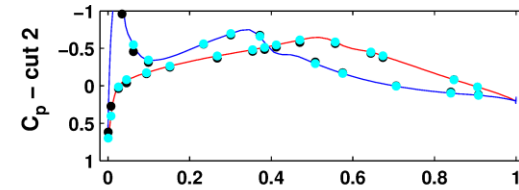
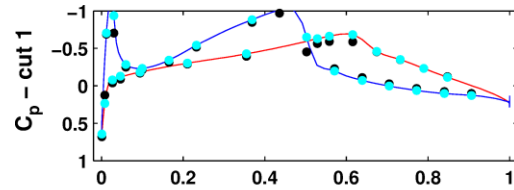
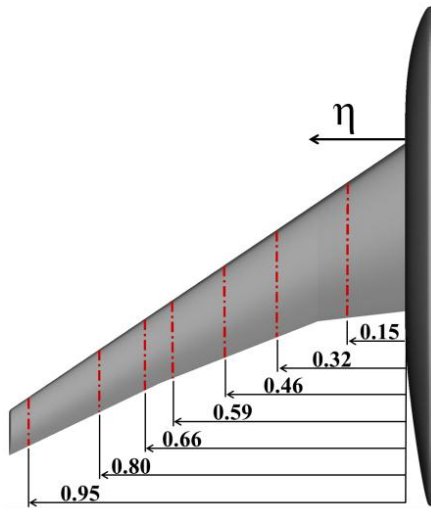
- AoA = 1.5°
- Ma = 0.8, Re = 7.0 million
- Medium mesh
- Deficiency in the shock region (pressure waves)



Results and validation of the steady simulations

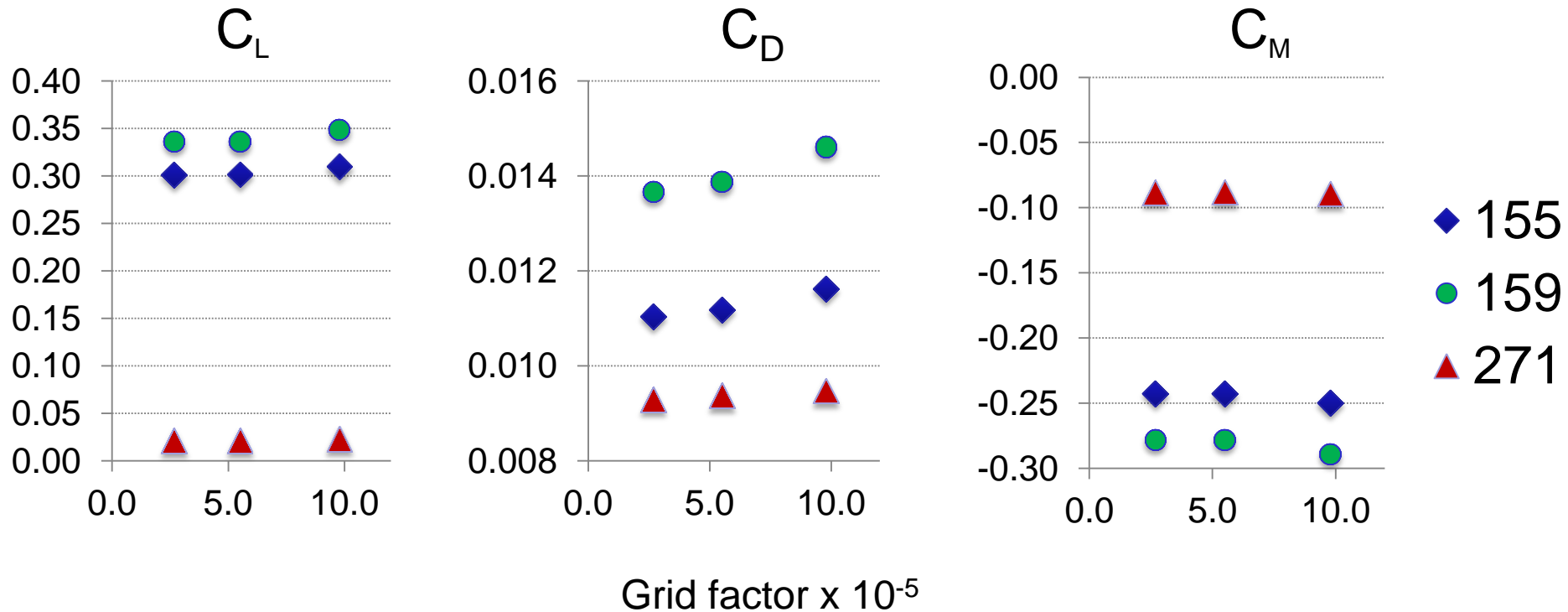
- Comparison of the static coupling results in terms of c_p for test case **271**

- AoA = 1.5°
- Ma = 0.8, Re = 7.0 million
- Medium mesh



Results and validation of the steady simulations

- Mesh convergence for the static coupling test cases



Approach for the unsteady forced motion simulations

- To simulate the unsteady test cases, the elastic motion of the wing in the second bending mode was applied as boundary condition during an unsteady CFD calculation

$$\begin{aligned}\vec{u}_{a,x}(t) &= a_0 \Phi_{a,x} \sin(\omega t) \\ \vec{u}_{a,y}(t) &= a_0 \Phi_{a,y} \sin(\omega t) \\ \vec{u}_{a,z}(t) &= a_0 \Phi_{a,z} \sin(\omega t)\end{aligned}$$

Amplitude a_0 of the simulation was chosen to match the experimental amplitude

- To obtain a transfer function of the pressure coefficient similar to the experimental data, the spectrum of c_p of the last period of oscillation is divided by the spectrum of the excitation signal (smooth function $\vec{u}_a(t)$)

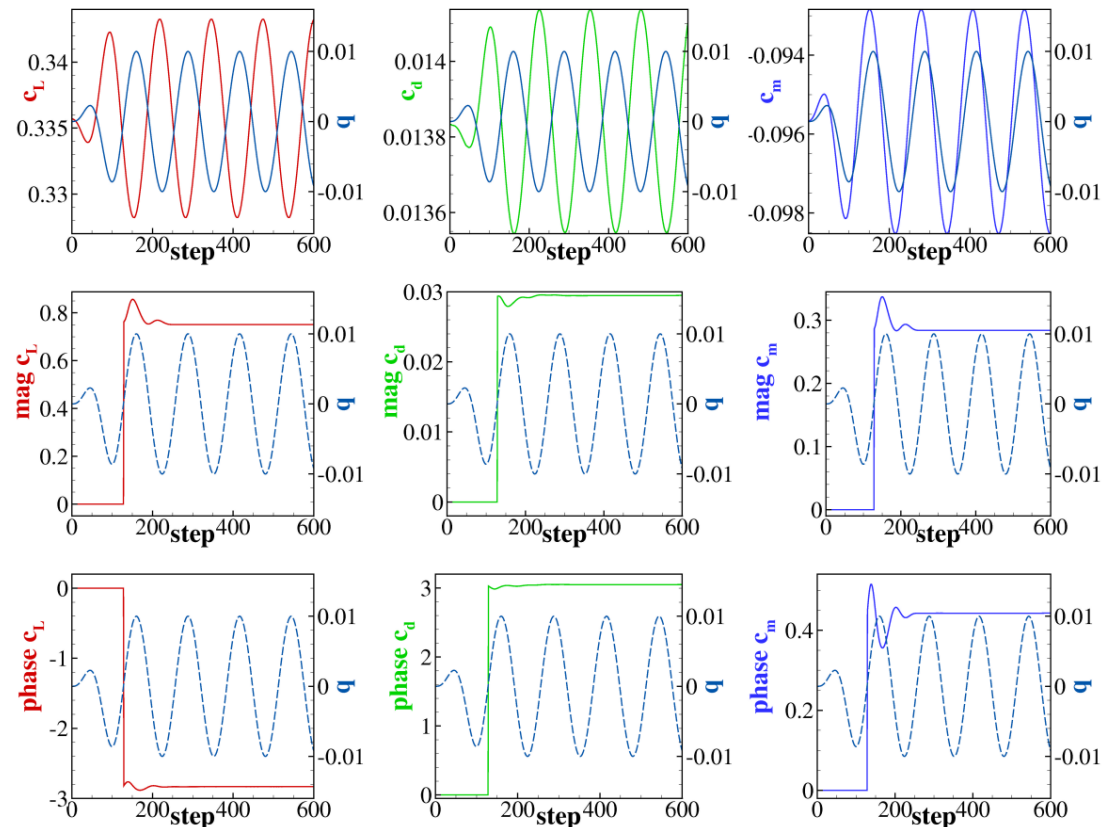
$$T_{CFD}(f) = \frac{FFT(c_p(t))}{FFT(a_0 \sin(\omega t))}$$



Approach for the unsteady forced motion simulations

- The following numerical parameter were used for the unsteady Forced Motion simulations:

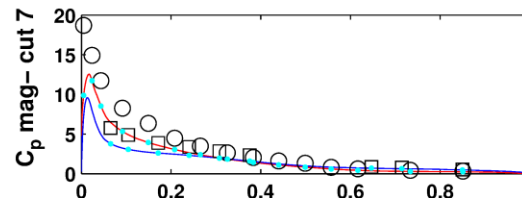
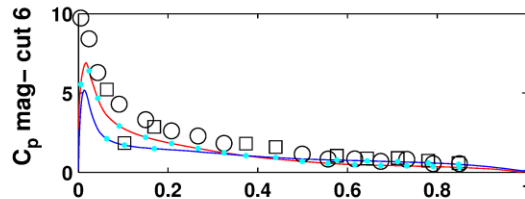
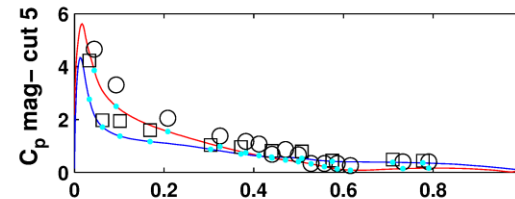
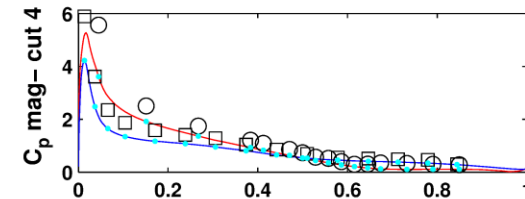
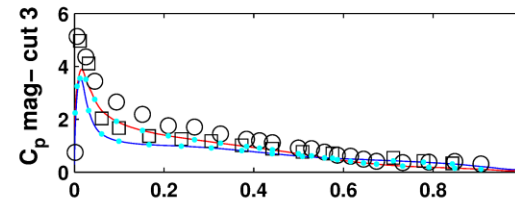
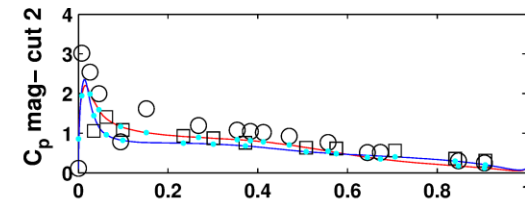
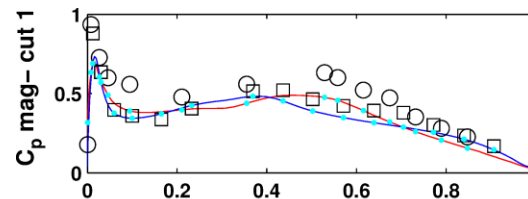
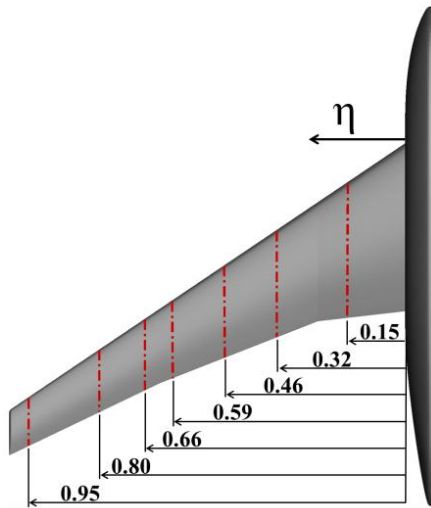
- Dual time stepping for time integration
- 64/128 physical steps per period
- Convergence in the frequency domain could be reached for integral values after approx. 2 oscillation periods



Results and validation of the unsteady simulations

- Comparison of c_p magnitude for test case 155

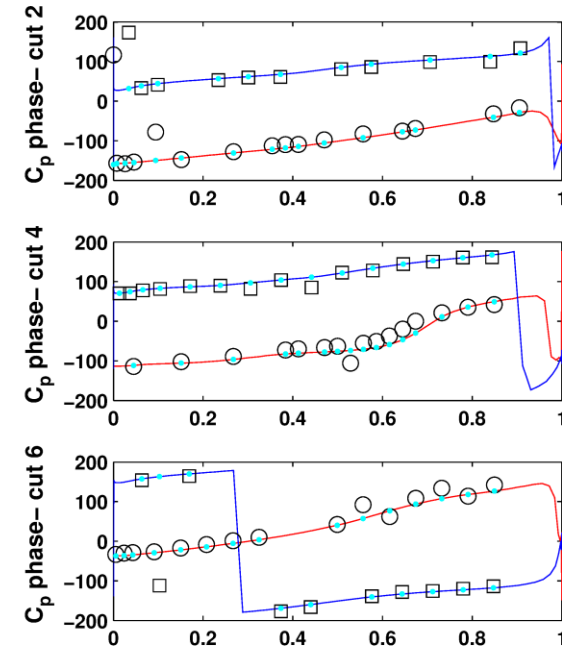
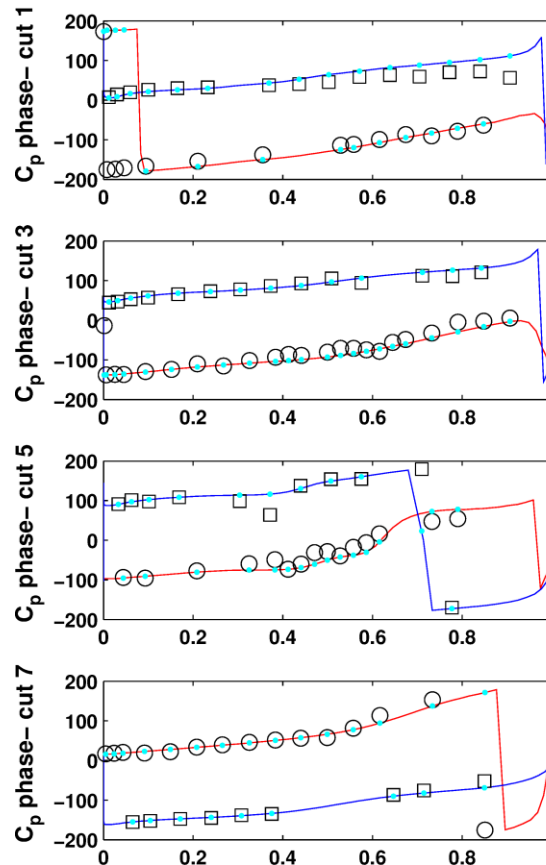
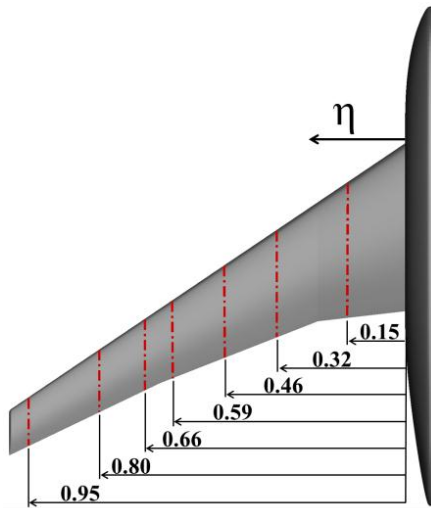
- AoA = 1.495°
- Ma = 0.7, Re = 7.0 million
- Medium mesh



Results and validation of the unsteady simulations

- Comparison of c_p phase for test case 155

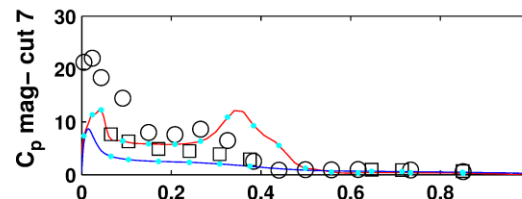
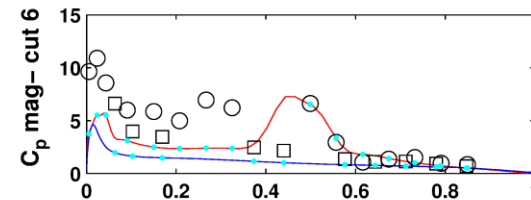
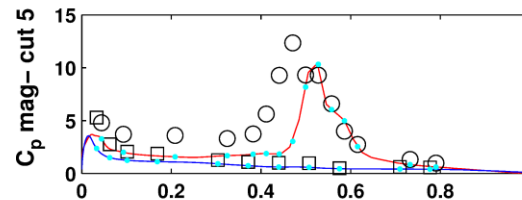
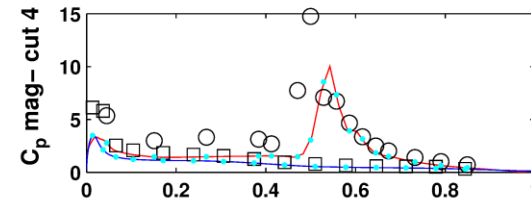
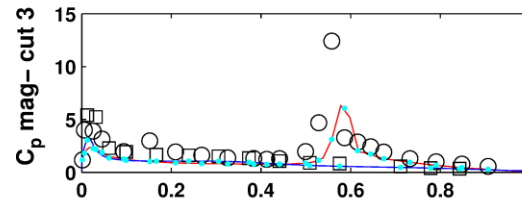
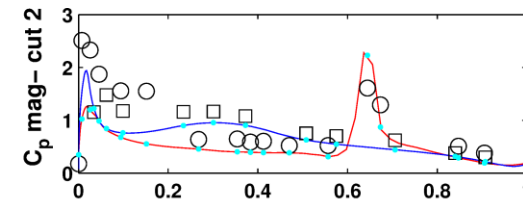
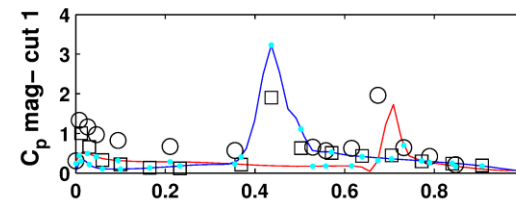
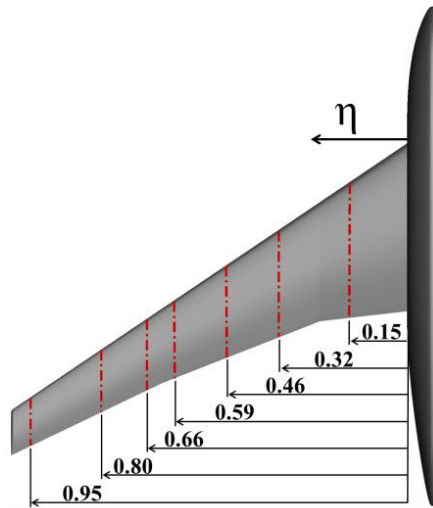
- AoA = 1.495°
- Ma = 0.7, Re = 7.0 million
- Medium mesh



Results and validation of the unsteady simulations

- Comparison of c_p magnitude for test case 159

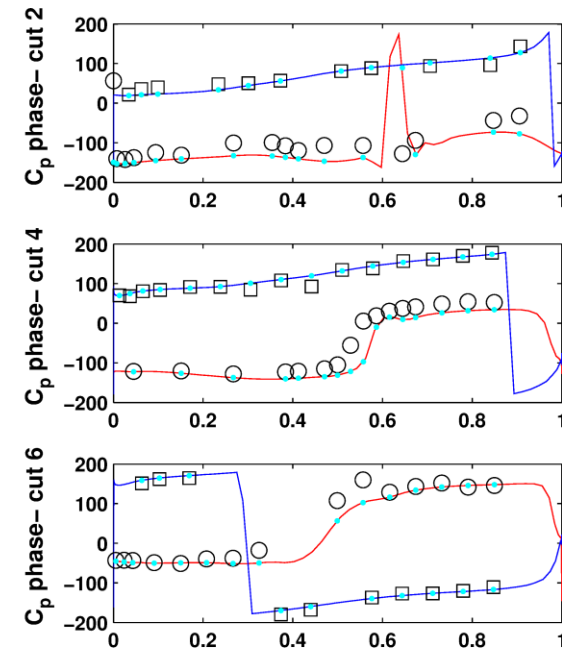
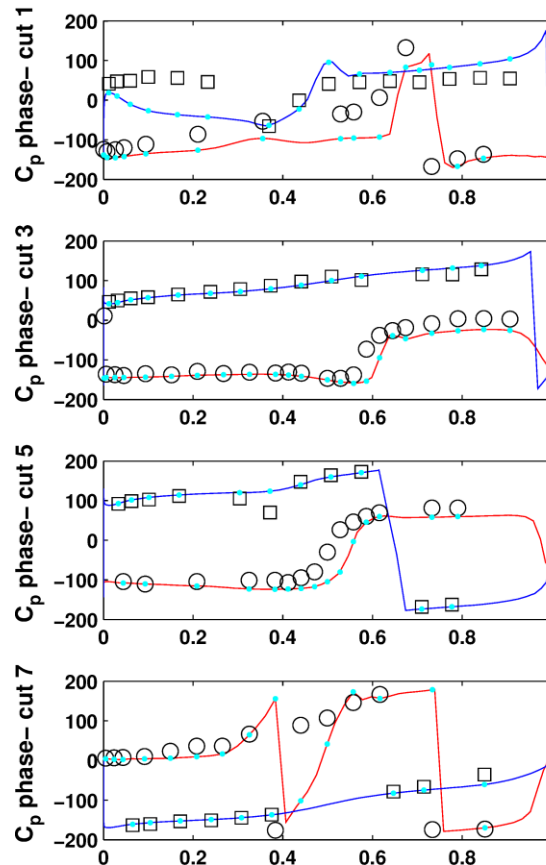
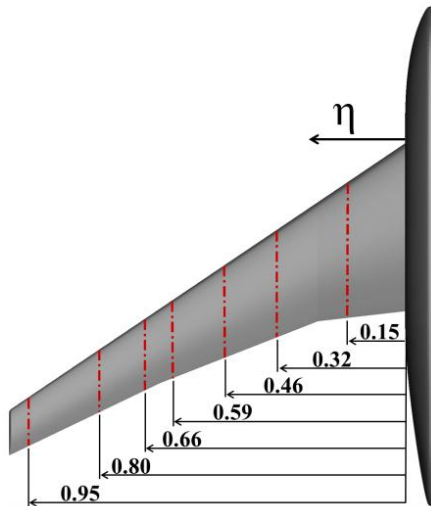
- AoA = 1.495°
- Ma = 0.8, Re = 7.0 million
- Medium mesh



Results and validation of the unsteady simulations

- Comparison of c_p phase for test case 159

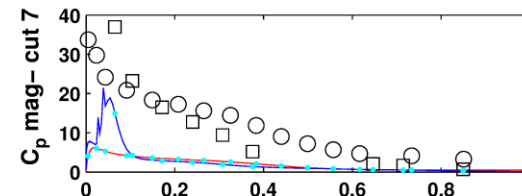
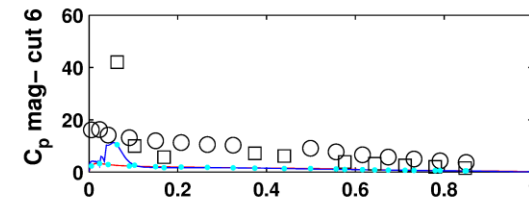
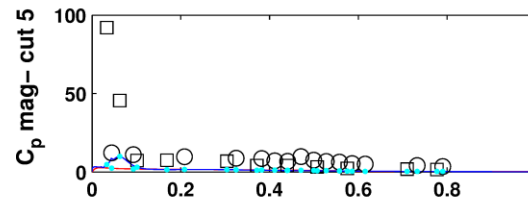
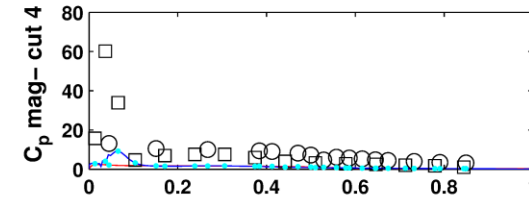
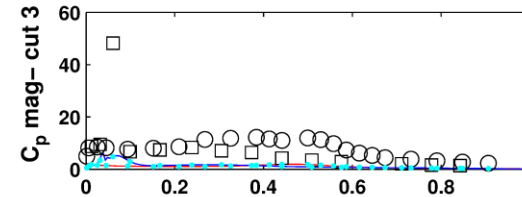
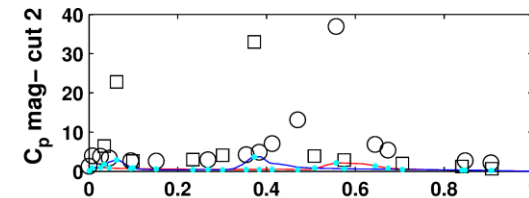
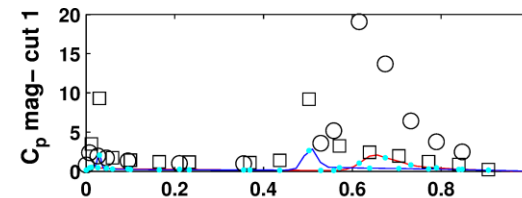
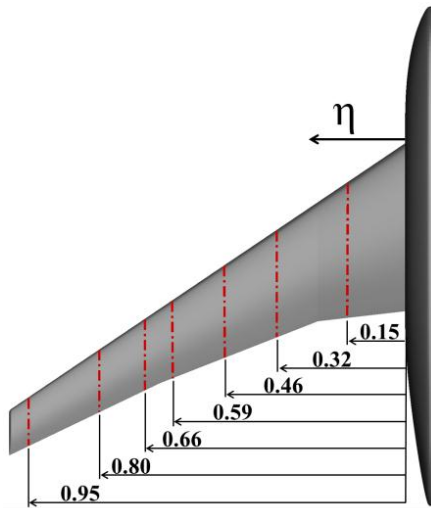
- AoA = 1.495°
- Ma = 0.8, Re = 7.0 million
- Medium mesh



Results and validation of the unsteady simulations

- Comparison of c_p magnitude for test case 271

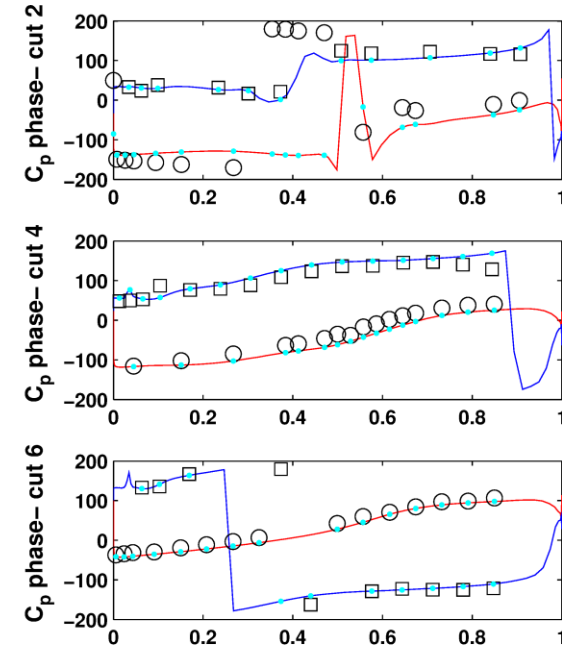
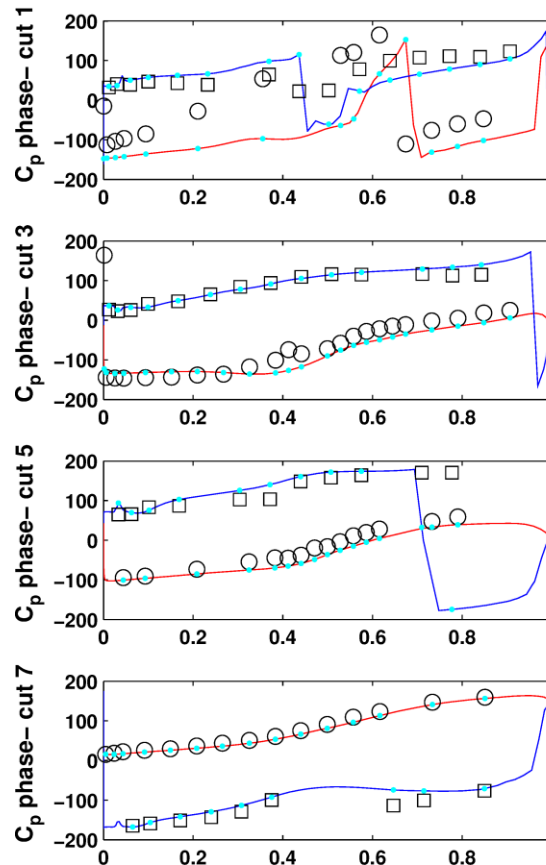
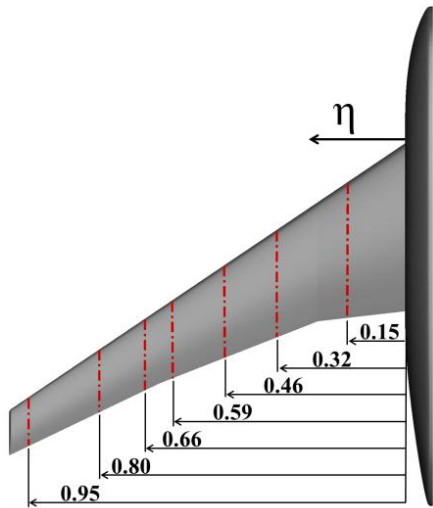
- AoA = 1.495°
- Ma = 0.8, Re = 23.5 million
- Medium mesh



Results and validation of the unsteady simulations

- Comparison of c_p phase for test case 271

- AoA = 1.495°
- Ma = 0.8, Re = 23.5 million
- Medium mesh



Conclusion

- Results of the *static coupling* simulations agree well with experimental data:
 - Modal approach seems sufficient for the calculation of the steady aeroelastic equilibrium
- Results of the unsteady forced motion simulations agree well with experimental data with respect to c_p phase
- Differences occur for c_p magnitude, further clarification is necessary by considering at least:
 - Shock location (Turbulence model?)
 - Amplitude of the motion
 - FE modelling
 - Experimental data



Thank you for your attention

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